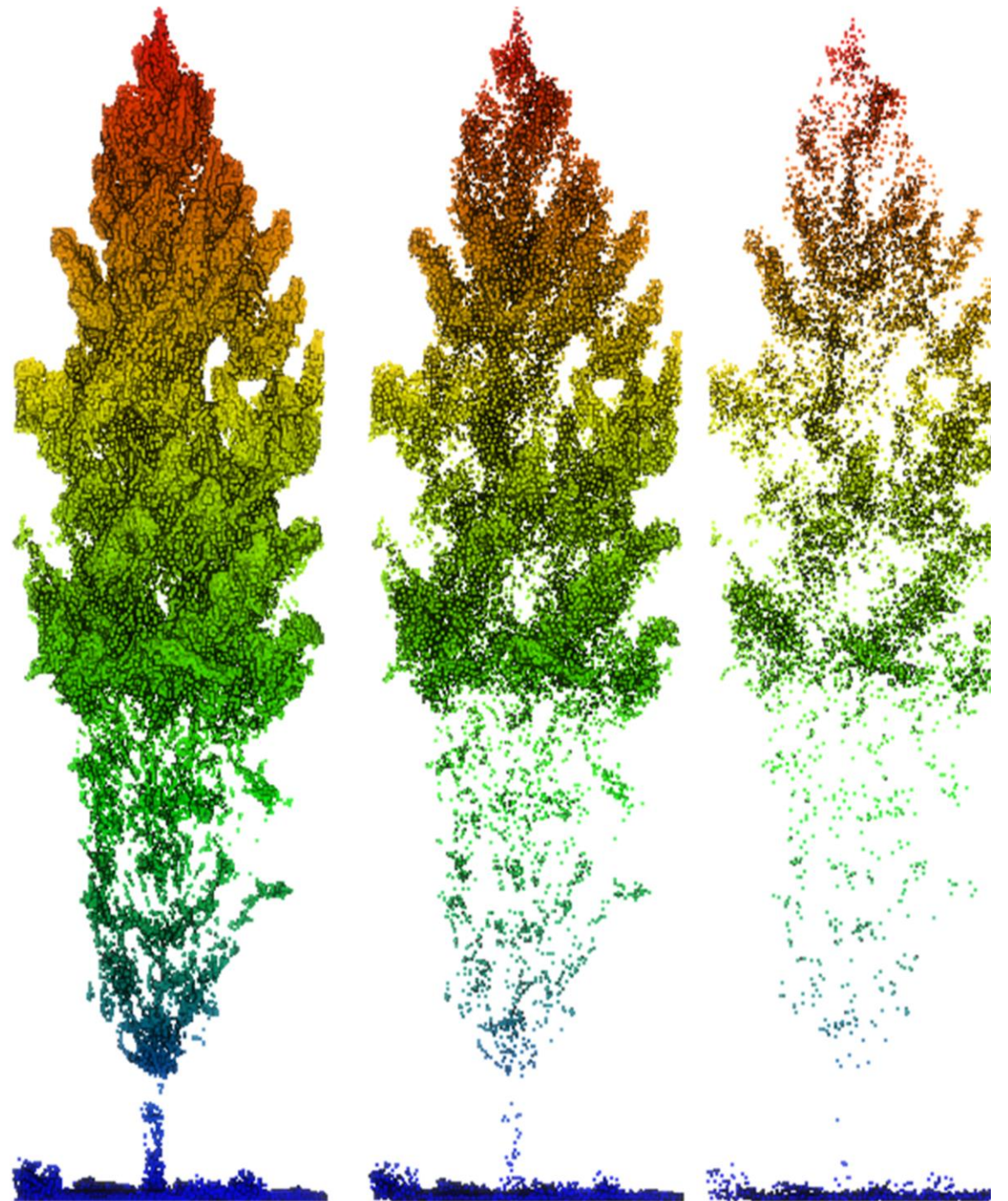


In-house LiDAR for  
forestry companies?  
An appraisal of the  
DJI L1 sensor for  
forest inventory

*Sadeepa Jayathunga*

*Robin Hartley*



# Sensor: DJI-L1 Zenmuse

- Consumer-grade solid-state LiDAR that integrates
  - a Lidar module
  - an RGB camera
  - a high-accuracy IMU
- Mounted on DJI Matrice 300 RTK
- 5 cm vertical and 10 cm horizontal accuracy
- Two scan modes: Repetitive and Non-repetitive
- Three pulse frequencies: 80, 160, 240 Hz
- Record up to three returns per laser pulse
- 2km<sup>2</sup> area coverage in a single flight





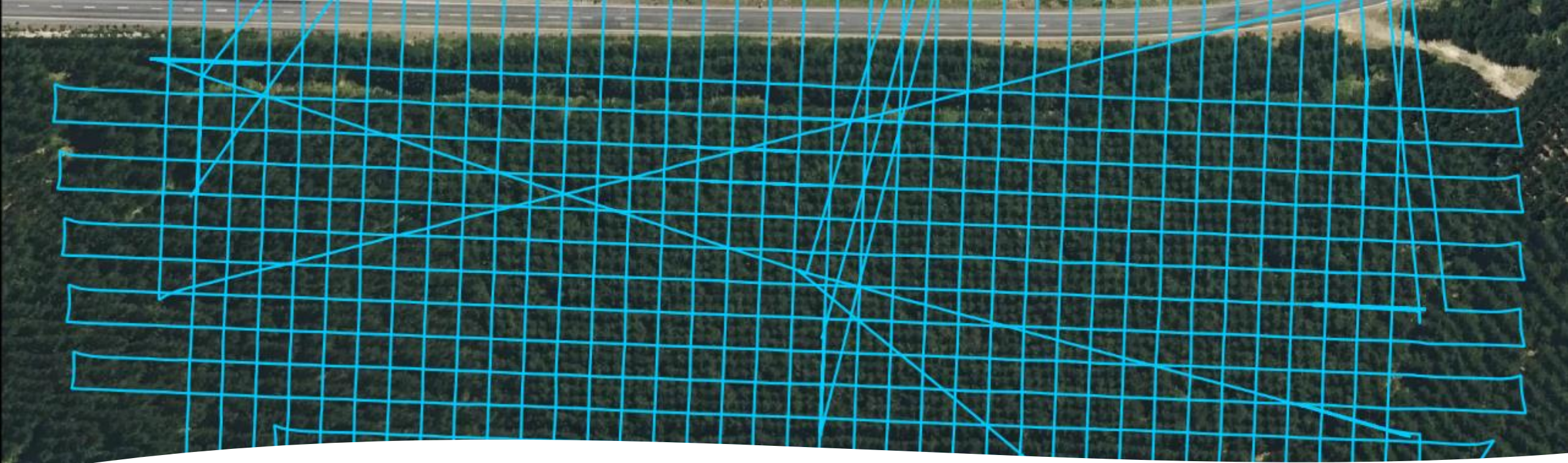
# Test site

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- 3 ha Radiata pine trial
- Age 9
- Stand density of 456 stems/ha
- Mostly flat terrain
- Moderately dense understory of thick Blackberry shrubs





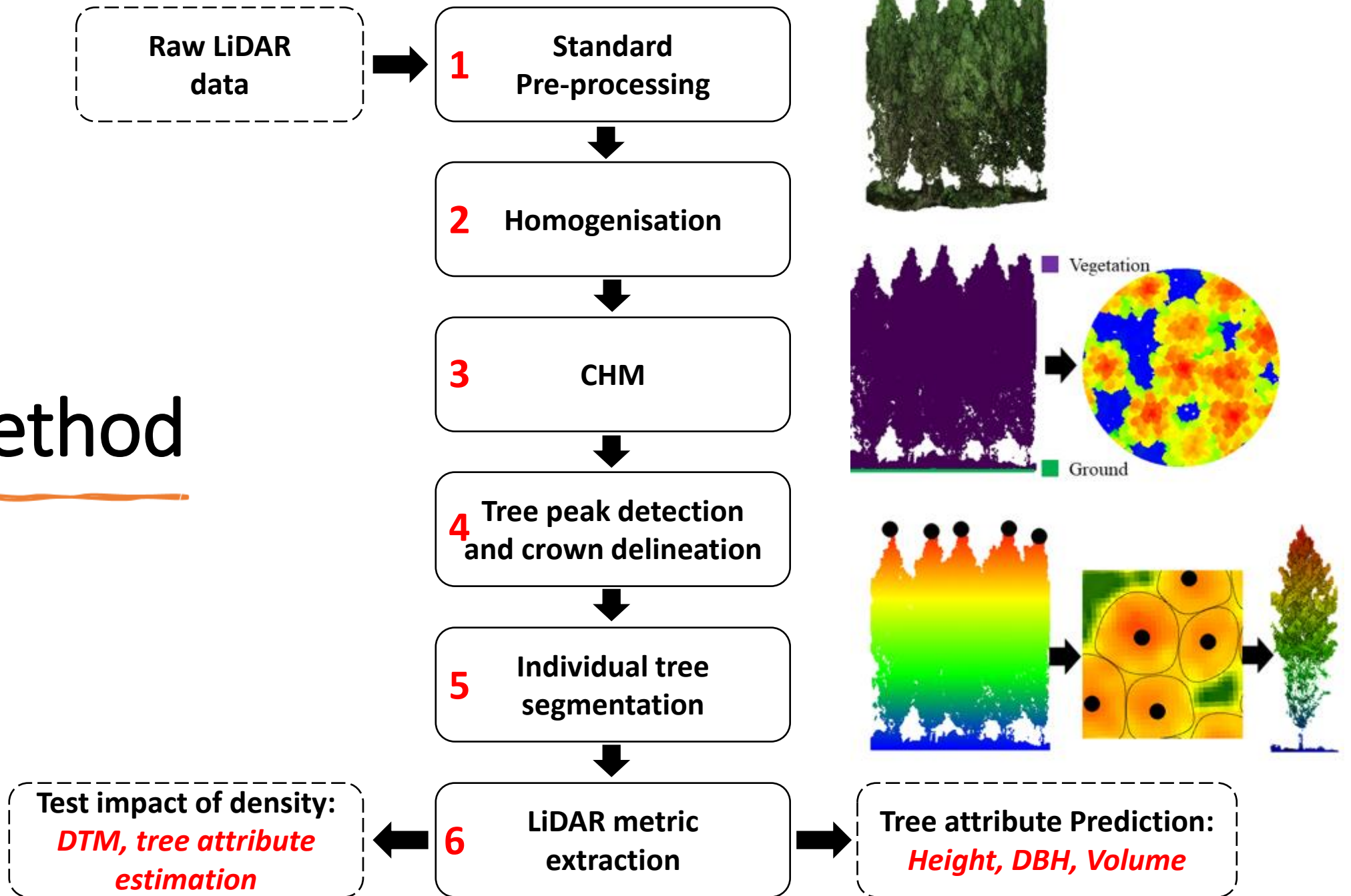


# Flight planning

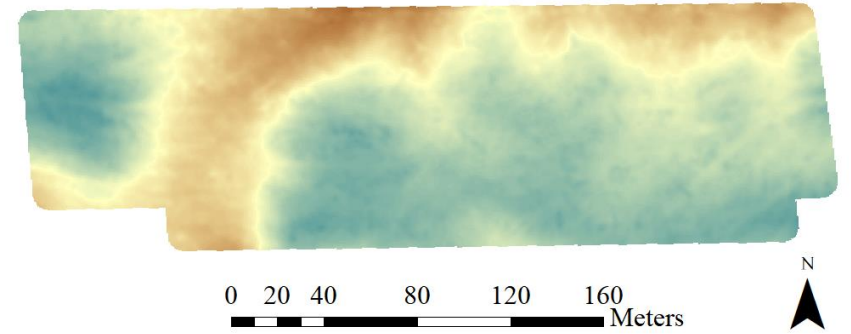
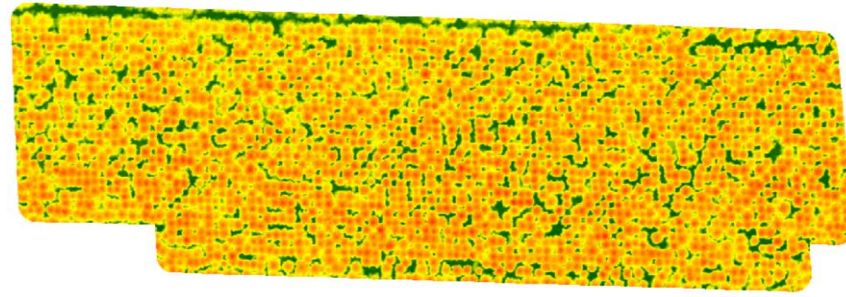
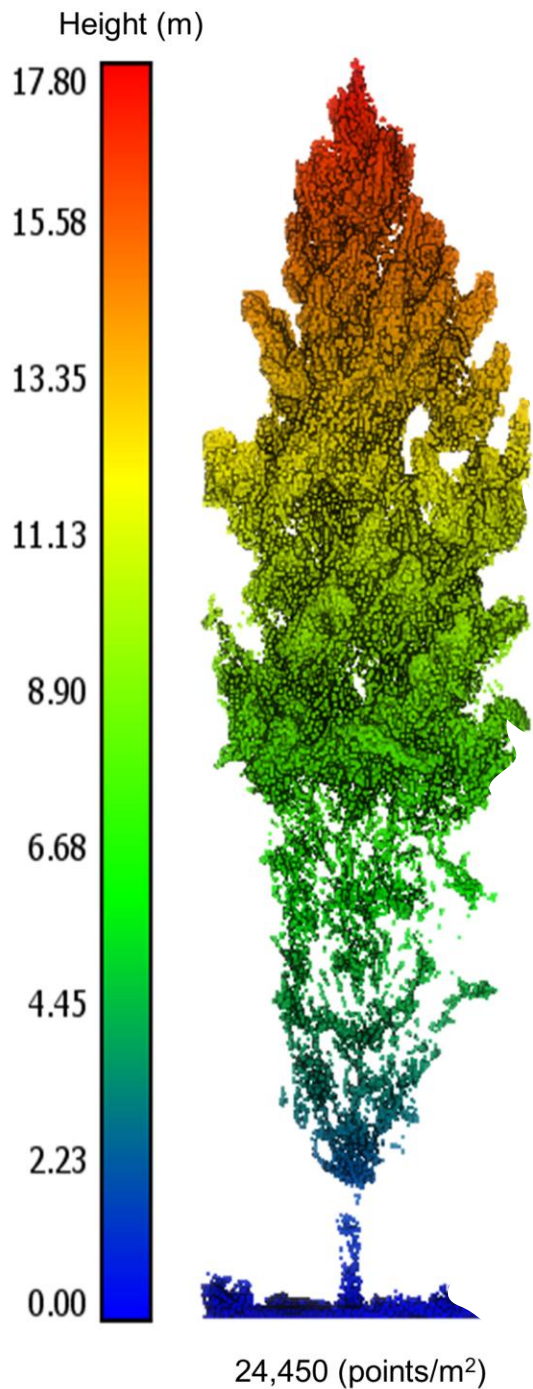
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- Gridded pattern: 10 m spacing between flight lines
- Flying speed: 3 m/s
- Altitude: 55 m above ground
- Scan mode: Repetitive
- Pulse frequency: 160 Hz
- 1 hour and 42 minutes flight time

# Method





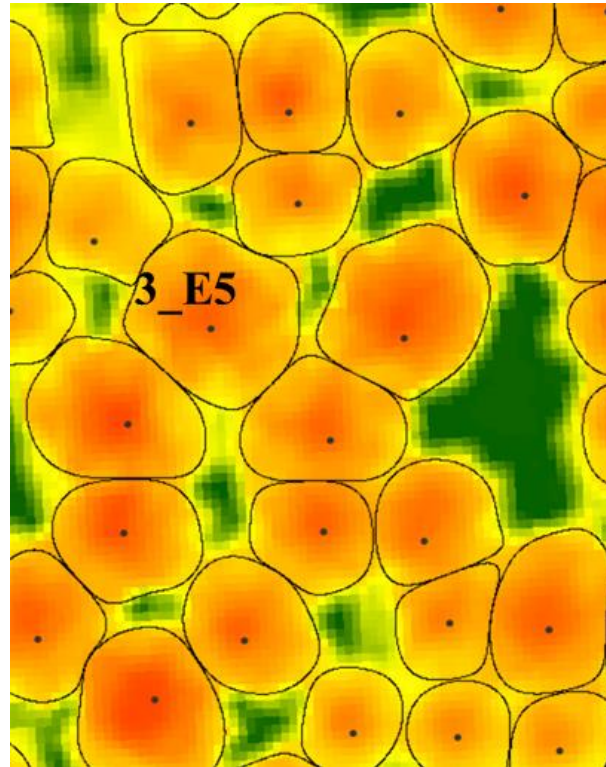


## Point cloud characteristics

- High average point density
  - Raw :  $\sim 45,966$  points/m<sup>2</sup>
  - Homogenised:  $24,450$  points/m<sup>2</sup>
- Good pulse penetration
  - Terrain characterisation
- Tree characterisation
  - Stem points
  - Foliage structure

# LiDAR metrics of individual trees

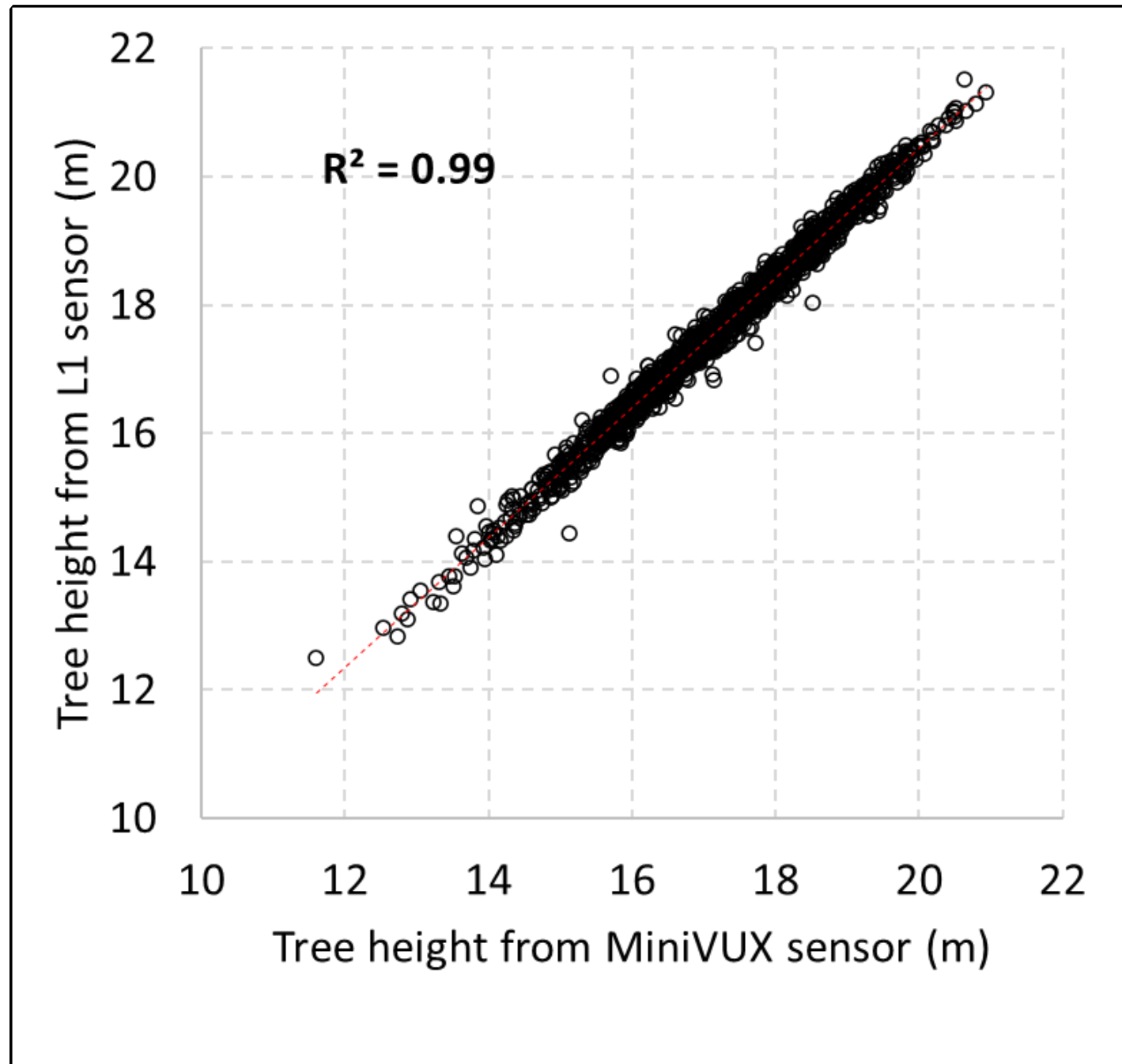
- Standard height and intensity metrics
- Area-based metrics (e.g., 2D crown area)
- 3D metrics (3D crown area and volume)
- Voxel-based metrics
- Gap fraction and LAI metrics



# Tree height

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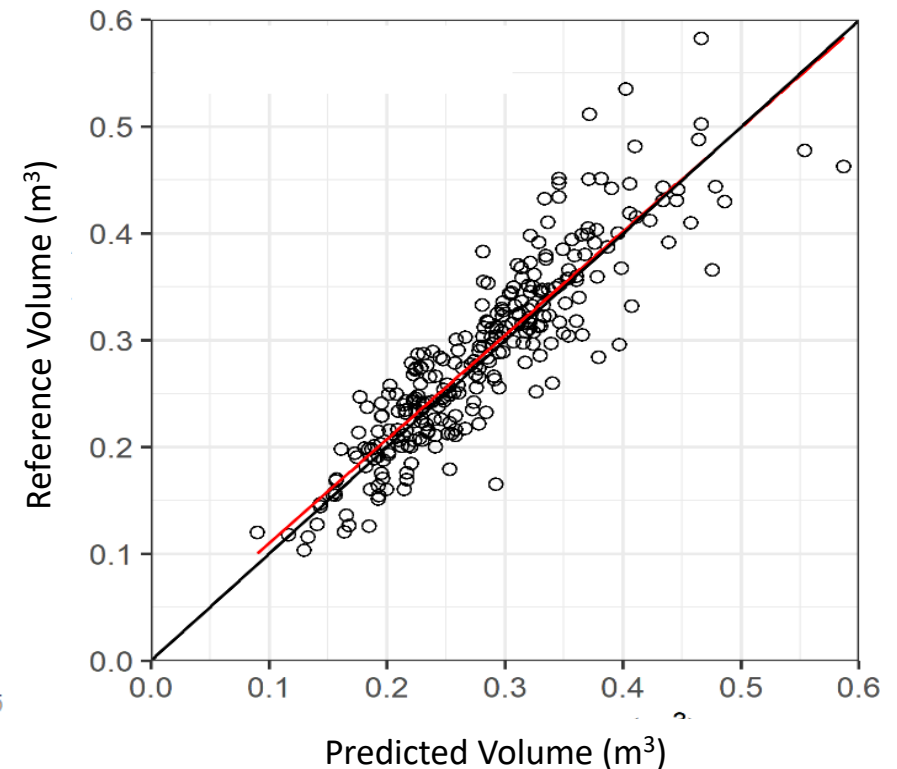
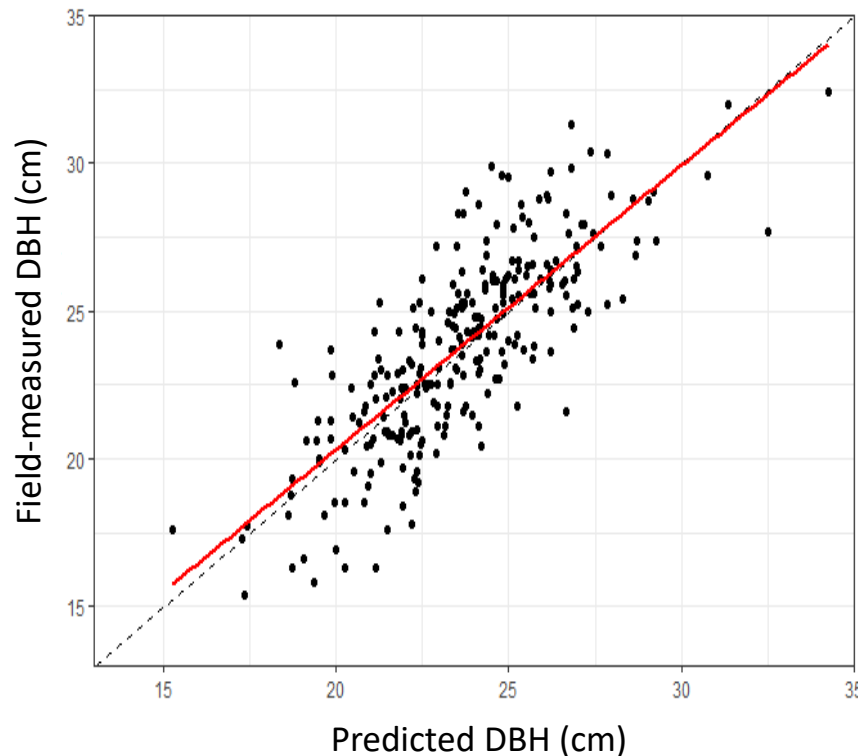
- Comparable accuracy to scientific grade and more expensive MiniVUX sensor





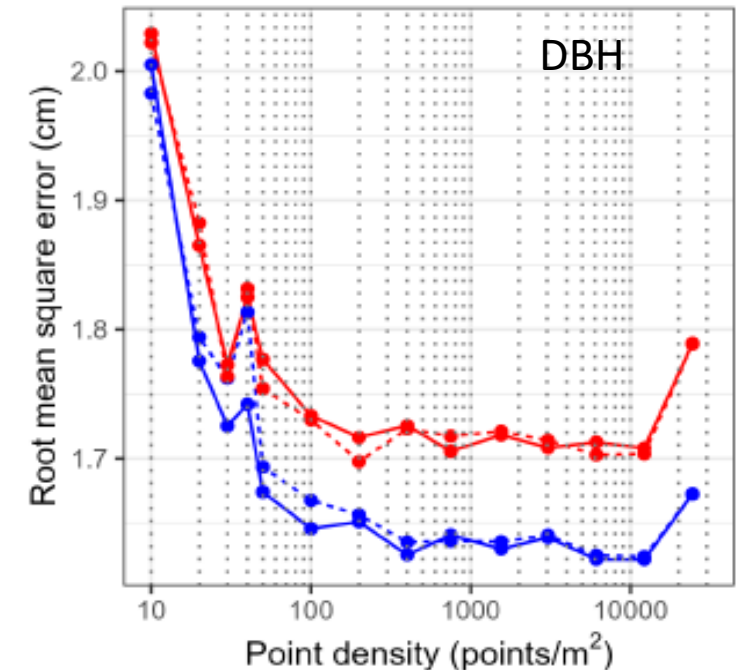
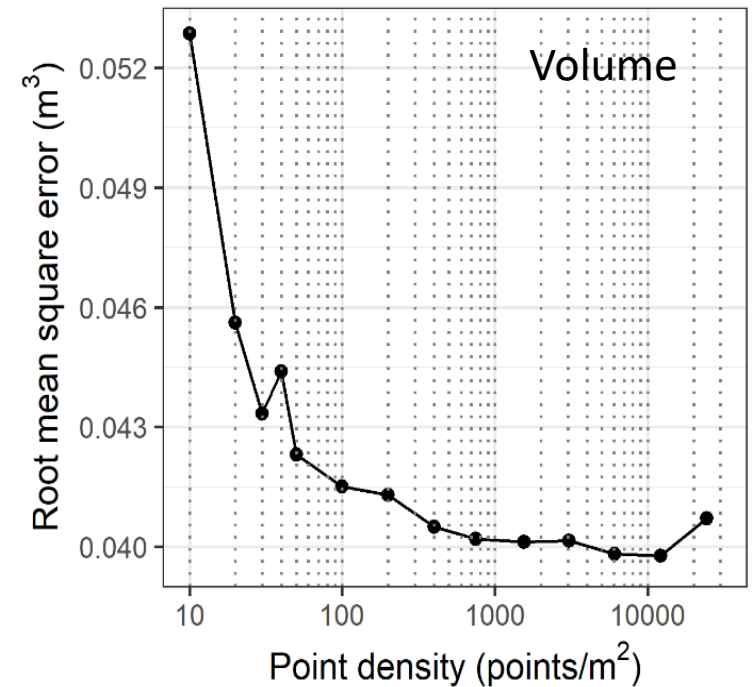
# Diameter at Breast Height (DBH) and Volume

- DBH predicted using two modelling methods (RF and PLS)
  - $R^2$ : 0.71
  - RMSE: 1.78 cm
- Volume predicted with  $R^2$  of 0.79
- **3D crown area** metric had the highest importance in predicting DBH



# Impact of point density on tree attribute prediction

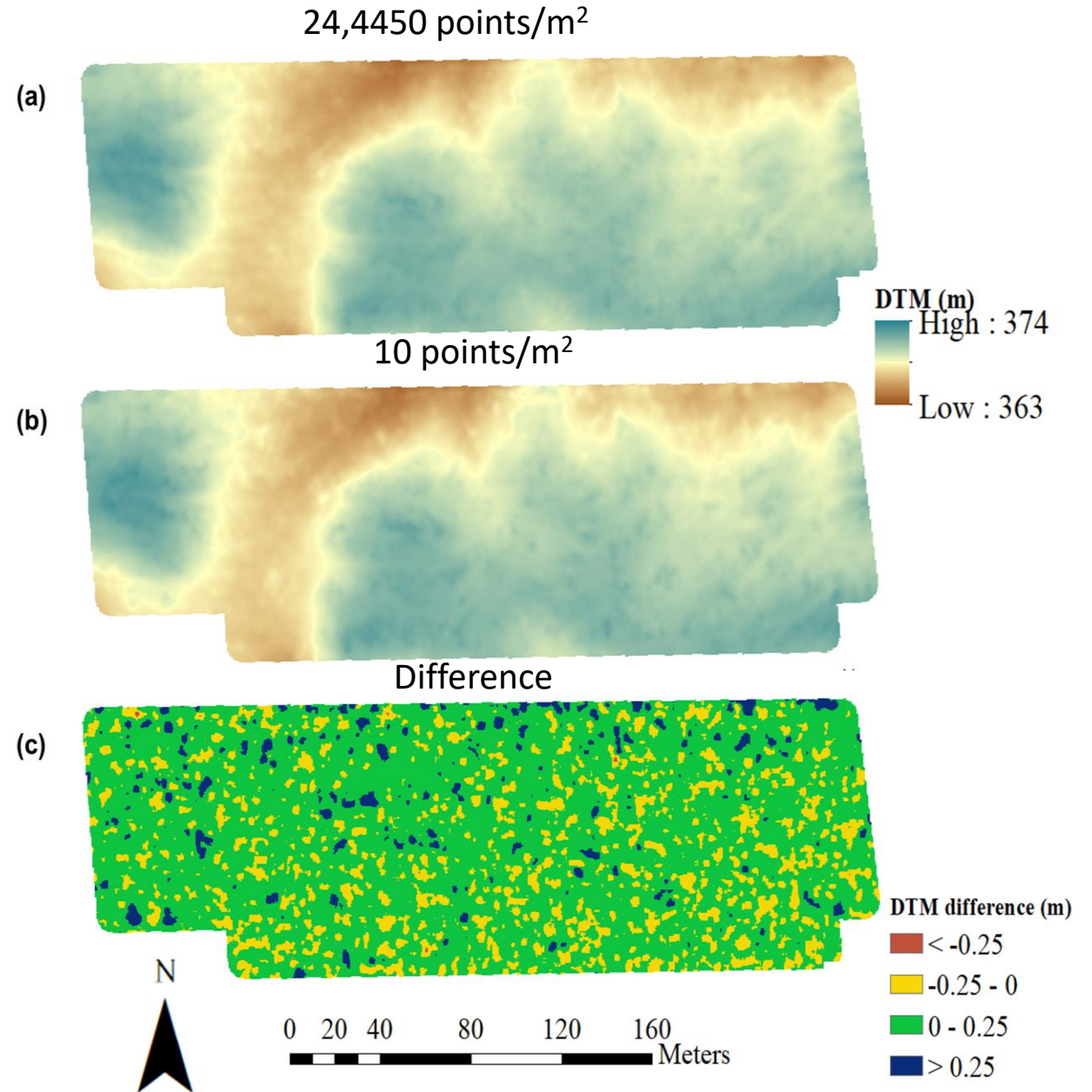
- Accuracy increased with increasing point density up to 400 points/m<sup>2</sup>
- Highest accuracy at 12,200 points/m<sup>2</sup>





# Impact of point density on DTM

- Tested 14 densities ranging between 10 and 24,450 points/m<sup>2</sup>
- No significant differences between DTMs created from varying point densities
- Maximum difference: 11 cm



# In conclusion

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- DJI-L1 sensor is capable of supplementing reliable information essential for forest inventory and assessment, including **DTMs, CHMs, tree segmentation and LiDAR metrics at individual tree level.**
- Important tree attributes like **height, DBH and stem volume** can be predicted with high accuracy using a range of 2D and 3D LiDAR metrics derived from DJI-L1 point clouds.
- Accuracy of these products increases with increasing density up to 400 points/m<sup>2</sup>.
- The flight time further highlights the potential of this consumer-grade sensors for the **rapid and frequent assessments and monitoring** of forest stands.



# Future implications

- Our findings demonstrated that these cost-effective LiDAR sensors offer **opportunities for forestry companies to enhance the application of LiDAR technology in their forest management activities.**
- **Exploring the application and versatility** of this sensor
  - in diverse forestry settings, including various tree species, age classes, terrains, and stand densities
  - to derive additional tree attributes



**Coming soon!!!**



Article

## Unlocking the potential of consumer-grade UAV laser scanners: a revolutionary tool for forest management.

Sadeepa Jayathunga<sup>1\*</sup>, Michael S. Watt<sup>2\*</sup>, Robin J. L. Hartley<sup>1</sup>, Grant D. Pearce<sup>1</sup>, Peter D. Massam<sup>1</sup>, David Cajés, Benjamin S.C. Steer<sup>1</sup>, and Honey Jane Estarija<sup>1</sup>

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\* Correspondence: sadeepa.jayathunga@scionresearch.com (S.J.); michael.watt@scionresearch.com (M.S.W.)

**Abstract:** The sustainable management of plantation forests necessitates precise inventory techniques. Unmanned aerial vehicle laser scanning (ULS) offers a cost-effective approach to accurately

# Acknowledging the efforts

---

- **Scion team:**

*Sadeepa Jayathunga, Michael S. Watt, Robin J. L. Hartley, Grant D. Pearse, Peter D. Massam, David Cajés, Benjamin S.C. Steer, Honey Jane Estarija, Warren Yorston, Samuel Wong, John Henry, Grant Evans, Joane Elleouet, and Russell Main*

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- **Inventory data collection:**

*Interpine Innovation*



*Thank You!*

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